

# Periodic Solution for a Class of Subquadratic Second-Order Hamiltonian Systems<sup>①</sup>

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**Abstract:** Some solvability conditions of periodic solution are obtained for a class of subquadratic Hamiltonian systems by the minimax methods in critical point theory.

**Key words:** subquadratic Hamiltonian systems; solvability conditions; periodic solution

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Consider the second-order Hamiltonian systems

$$\begin{aligned} -\ddot{u}(t) + A(t)u &= \nabla F(t, u(t)) & \text{a. e. } t \in [0, T] \\ u(0) - u(T) &= \dot{u}(0) - \dot{u}(T) = 0 \end{aligned} \quad (1)$$

where  $A(t)$  is a continuous symmetric matrix of order  $N$  and  $F: R \times R^N \rightarrow R$  satisfies the following assumption:

(A)  $F(t, x)$  is measurable in  $t$  for all  $x \in R^N$ , continuously differentiable in  $x$  for a. e.  $t \in [0, T]$ , and there exist  $a \in C(R^+, R^+)$  and  $b \in L^1(0, T; R^+)$  such that

$$|F(t, x)| \leq a(|x|)b(t) \quad |\nabla F(t, x)| \leq a(|x|)b(t)$$

for all  $x \in R^N$  and a. e.  $t \in [0, T]$ .

With the aids of the variational methods, the existence of periodic solutions for systems (1) is obtained in [1–9]. In the case  $A(t) = 0$ , there are many solvability conditions for systems (1), such as the coercive type potential condition (see [1]), the convex and subconvex type potential condition (see [2–4]), the even type potential condition (see [5]), the subquadratic potential condition (see [6–8]). Recently, [7] has obtained the existence of periodic solution for systems (1) under the subquadratic condition where  $A(t) = 0$ . In this paper, we will obtain the existence of periodic solution for systems (1) under the subquadratic condition. Obviously, Theorem 1 in the paper greatly extends Theorem 2 in [7] which is a special case of our Theorem 1, and Theorem 2 extends Theorem 3 in [8] because the subquadratic potential condition proposed in the following in the paper is more general than that one in [8]. Our main results are the following theorems:

**Theorem 1** Suppose that  $F$  satisfies assumption (A). If the linear second order systems

$$\begin{aligned} -\ddot{u}(t) + A(t)u &= \lambda_{k-1}u(t) & \text{a. e. } t \in [0, T] \\ u(0) - u(T) &= \dot{u}(0) - \dot{u}(T) = 0 \end{aligned} \quad (2)$$

has a nonzero solution assume that

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$$\lim_{|x| \rightarrow \infty} [x \cdot \nabla F(t, x) - 2F(t, x)] = -\infty \quad \text{a. e. } t \in [0, T] \quad (3)$$

Assume that there exist consecutive eigenvalues  $\lambda_{k-1}, \lambda_k$  of the operator  $-\frac{d^2}{dt^2} + A(t)$  such that

$$\lambda_{k-1} \leq \liminf_{|x| \rightarrow \infty} \frac{2F(t, x)}{|x|^2} \leq \limsup_{|x| \rightarrow \infty} \frac{2F(t, x)}{|x|^2} < \lambda_k \quad \text{a. e. } t \in [0, T] \quad (4)$$

Then there exists a  $T$ -periodic solution of systems (1).

**Theorem 2** Suppose that  $F$  satisfies assumption (A) and the following condition:

$$\lim_{|x| \rightarrow \infty} [x \cdot \nabla F(t, x) - 2F(t, x)] = +\infty \quad \text{a. e. } t \in [0, T] \quad (5)$$

Assume that there exist consecutive eigenvalues  $\lambda_{k-1}, \lambda_k$  of the operator  $-\frac{d^2}{dt^2} + A(t)$  such that

$$\lambda_{k-1} < \liminf_{|x| \rightarrow \infty} \frac{2F(t, x)}{|x|^2} \leq \limsup_{|x| \rightarrow \infty} \frac{2F(t, x)}{|x|^2} \leq \lambda_k \quad \text{a. e. } t \in [0, T] \quad (6)$$

Then there exists a  $T$ -periodic solution of systems (1).

Now, we give some preliminaries.

It is well known that  $u$  is a  $T$ -periodic solution of system (1) if and only if  $u$  is a critical point of the functional  $\varphi$  in  $H_T^1$ , where

$$H_T^1 = \left\{ u: [0, T] \rightarrow \mathbb{R}^N \mid \begin{array}{l} u \text{ is absolutely continuous,} \\ u(0) = u(T) \text{ and } \dot{u} \in L^2(0, T; \mathbb{R}^N) \end{array} \right\}$$

is a Hilbert space with the norm  $\|u\| = \left( \int_0^T |u|^2 dt + \int_0^T |\dot{u}|^2 dt \right)^{\frac{1}{2}}$ , for  $u \in H_T^1$ , and

$$\varphi(u) = \frac{1}{2} \int_0^T [|\dot{u}|^2 + (A(t)u, u)] dt - \int_0^T F(t, u) dt \quad u \in H_T^1$$

It follows from Theorem 1.4 in [9] that  $\varphi \in C^1(H_T^1, \mathbb{R})$  and

$$\langle \varphi'(u), v \rangle = \int_0^T [(\dot{u}, \dot{v}) + (A(t)u, v)] dt - \int_0^T (\nabla F(t, u), v) dt \quad u, v \in H_T^1$$

where  $(\cdot, \cdot)$  and  $|\cdot|$  are the usual inner product and norm of  $\mathbb{R}^N$ .

**Lemma 1** Suppose (A), (2) and (3) hold. Then function  $\varphi$  satisfies condition (C).

**Proof** By contradiction, let  $c \in \mathbb{R}$  and suppose  $\{u_n\} \subset H_T^1$  such that  $\|u_n\| \rightarrow \infty$ ,  $\varphi(u_n) \rightarrow c$  and  $(1 + \|u_n\|) \|\varphi'(u_n)\| \rightarrow 0$  as  $n \rightarrow \infty$ . It follows that

$$\lim_{n \rightarrow \infty} [\langle \varphi'(u_n), u_n \rangle - 2\varphi(u_n)] = 2c$$

More precisely, we have

$$\lim_{n \rightarrow \infty} \int_0^T [(\nabla F(t, u_n), u_n) - 2F(t, u_n)] dt = 2c \quad (7)$$

Put  $z_n = \frac{u_n}{\|u_n\|}$ , we have  $\|z_n\| = 1$ , without loss of generality we may assume that:  $z_n \rightarrow z$  weakly in  $H_T^1$ ,

$z_n \rightarrow z$  strongly in  $L^2(0, T)$  and  $z_n(t) \rightarrow z(t)$  for a. e.  $t \in [0, T]$ .

Let  $\epsilon_1 = \left( \frac{1}{2} \lambda_k - \limsup_{|x| \rightarrow \infty} \frac{F(t, x)}{|x|^2} \right) / 2 > 0$ , by (3), there exists  $\delta > 0$ , such that

$$F(t, x) \leq \frac{1}{2} (\lambda_k - \epsilon_1) |x|^2 \quad |x| \geq \delta, \text{ a. e. } t \in [0, T]$$

By assumption (A), it's easy to know that  $|F(t, x)| \leq \max_{s \in [0, \delta]} a(s)b(t)$  for all  $|x| \leq \delta$  and a. e.  $t \in [0, T]$ .

Hence, we obtain

$$F(t, x) \leq \frac{1}{2} (\lambda_k - \epsilon_1) |x|^2 + g(t) \quad (8)$$

for all  $x \in \mathbb{R}^N$  and a. e.  $t \in [0, T]$  where  $g(t) = \max_{s \in [0, \delta]} a(s)b(t) + \frac{1}{2} |\lambda_k| \delta^2$ . By (8), we have

$$\begin{aligned}
\varphi(u_n) &= \frac{1}{2} \int_0^T [|\dot{u}_n|^2 + (A(t)u_n, u_n)] dt - \int_0^T F(t, u_n) dt \\
&= \frac{1}{2} \|u_n\|^2 + \frac{1}{2} \int_0^T [(A(t)u_n, u_n) - |u_n|^2] dt - \int_0^T F(t, u_n) dt \\
&\geq \frac{1}{2} \|u_n\|^2 - \frac{1}{2} (c_1 + 1) \int_0^T |u_n|^2 dt - \frac{1}{2} (\lambda_k - \varepsilon_1) \int_0^T |u_n|^2 dt - \|g\|_{L^1} \\
&\geq \frac{1}{2} \|u_n\|^2 - \frac{1}{2} (c_1 + 1) \int_0^T |u_n|^2 dt - \frac{1}{2} \lambda_k \int_0^T |u_n|^2 dt - \|g\|_{L^1}
\end{aligned}$$

where  $c_1 = \max_{t \in [0, T]} |A(t)|$ . Therefore, one obtains

$$\frac{\varphi(u_n)}{\|u_n\|^2} \geq \frac{1}{2} (1 - (c_1 + 1 + \lambda_k) \|z_n\|_{L^2}^2) - \frac{\|g\|_{L^1}}{\|u_n\|^2}$$

Passing to the limit in the inequality, by using  $\varphi(u_n) \rightarrow c$  as  $n \rightarrow \infty$ , we obtain

$$\frac{1}{2} [1 - (c_2 + 1 + \lambda_k) \|z\|_{L^2}^2] \leq 0$$

which implies that  $z \neq 0$ .

Now by (2), there exists  $\delta_0 > 0$  such that  $(\nabla F(t, x), x) - 2F(t, x) \leq 0$  for all  $|x| \geq \delta_0$  and a. e.  $t \in [0, T]$  and by assumption (A) we have  $(\nabla F(t, x), x) - 2F(t, x) \leq c_2 b(t)$  for all  $|x| \leq \delta_0$  and a. e.  $t \in [0, T]$  where  $c_2 = (2 + \delta_0) \max_{s \in [0, \delta_0]} a(s)b(t)$ . So we get

$$(\nabla F(t, x), x) - 2F(t, x) \leq c_2 b(t)$$

for all  $x \in R^N$  and a. e.  $t \in [0, T]$ . Hence we get

$$\begin{aligned}
&\int_0^T [(\nabla F(t, u_n), u_n) - 2F(t, u_n)] dt \\
&= \int_{\{t, z(t) \neq 0\}} [(\nabla F(t, u_n), u_n) - 2F(t, u_n)] dt + \int_{[0, T] \setminus \{t, z(t) \neq 0\}} [(\nabla F(t, u_n), u_n) - 2F(t, u_n)] dt \\
&\leq \int_{\{t, z(t) \neq 0\}} [(\nabla F(t, u_n), u_n) - 2F(t, u_n)] dt + \int_{[0, T] \setminus \{t, z(t) \neq 0\}} c_2 b(t) dt
\end{aligned}$$

An application of Fatou's lemma yields

$$\int_0^T [(\nabla F(t, u_n), u_n) - 2F(t, u_n)] dt \rightarrow -\infty \quad n \rightarrow \infty$$

which is a contradiction to (7). In a similar way to Proposition 4.3 in [9], we can prove that  $\{u_n\}$  has a convergent subsequence. Thus, the proof of Lemma 1 is complete.

Now we give the proofs of the main results.

**Proof of Theorem 1** Let  $H_T^1 = H^0 \oplus H^+ \oplus H^-$ . where  $H^+ \triangleq_{j > k-1} \text{Ker}(-\frac{d^2}{dt^2} + A(t) - \lambda_j I)$ ,  $H^- \triangleq_{j < k-1} \text{Ker}(-\frac{d^2}{dt^2} + A(t) - \lambda_j I)$ ,  $H^0 = \text{Ker}(-\frac{d^2}{dt^2} + A(t) - \lambda_{k-1} I)$ . By the Saddle Point Theorem (see Theorem 2.13 in [10]), we only need to prove

$$(I_1) \inf_{H^+} \varphi(u) \geq d, \text{ where } d \text{ is a constant.}$$

$$(I_2) \sup_{H^- \oplus H^0} \varphi(u) < +\infty.$$

It follows from (8) that

$$\begin{aligned}
\varphi(u) &= \frac{1}{2} \int_0^T [|\dot{u}|^2 + (A(t)u, u)] dt - \int_0^T F(t, u) dt \\
&\geq \frac{1}{2} \int_0^T [|\dot{u}|^2 + (A(t)u, u)] dt - \frac{1}{2} (\lambda_k - \varepsilon_1) \|u\|_{L^2}^2 - \|g\|_{L^1} \\
&\geq \frac{1}{2} \lambda_k \|u\|_{L^2}^2 - \frac{1}{2} (\lambda_k - \varepsilon_1) \|u\|_{L^2}^2 - \|g\|_{L^1} \geq \frac{1}{2} \varepsilon_1 \|u\|_{L^2}^2 - \|g\|_{L^1} \geq -\|g\|_{L^1}
\end{aligned}$$

for all  $u \in H^+$ , which implies (I<sub>1</sub>).

Now, we prove (I<sub>2</sub>). Let's suppose that  $G(t, x) = F(t, x) - \frac{1}{2}\lambda_{k-1} |x|^2$ . By (2), we obtain, for every  $\beta > 0$ , there exists  $\delta_1 > 0$  such that

$$x \cdot \nabla G(t, x) - 2G(t, x) \leq -2\beta \quad |x| \geq \delta_1, \text{ a. e. } t \in [0, T] \tag{9}$$

Let  $s \geq 1$ , using (9) and integrating the relation

$$\frac{d}{ds} \left[ \frac{G(t, sx)}{s^2} \right] = \frac{sx \cdot \nabla G(t, sx) - 2G(t, sx)}{s^3} \leq \frac{-\beta}{s^3}$$

over an interval  $[1, S] \subset [1, \infty)$ , we get

$$\frac{G(t, Sx)}{S^2} - G(t, x) \leq \beta \left[ \frac{1}{S^2} - 1 \right]$$

Since  $\liminf_{s \rightarrow \infty} \frac{G(t, Sx)}{S^2} \geq 0$  by (3), we obtain  $G(t, x) \geq \beta$  for all  $|x| \geq \delta_1$  and a. e.  $t \in [0, T]$ . By assumption (A), we can get

$$|G(t, x)| = |F(t, x) - \frac{1}{2}\lambda_{k-1} |x|^2| \leq \max_{s \in [0, \delta_1]} a(s) b(t) + \frac{1}{2} |\lambda_{k-1}| \delta_1^2$$

for all  $|x| \leq \delta_1$  and a. e.  $t \in [0, T]$ . That's

$$G(t, x) = F(t, x) - \frac{1}{2}\lambda_{k-1} |x|^2 \geq \beta - \max_{s \in [0, \delta_1]} a(s) b(t) + \frac{1}{2} |\lambda_{k-1}| \delta_1^2 \tag{10}$$

for all  $x \in R^N$  and a. e.  $t \in [0, T]$ .

For all  $u = u^- + u^0 \in H^- \oplus H^0$ , we have

$$\begin{aligned} \varphi(u) &= \frac{1}{2} \int_0^T [|\dot{u}|^2 + (A(t)u, u)] dt - \frac{1}{2} \lambda_{k-1} \int_0^T |u|^2 dt - \int_0^T [F(t, u) - \frac{1}{2} \lambda_{k-1} |u|^2] dt \\ &\leq - \int_0^T [F(t, u) - \frac{1}{2} \lambda_{k-1} |u|^2] dt \leq \max_{s \in [0, \delta_1]} a(s) \|b\|_{L^1} + \frac{1}{2} |\lambda_{k-1}| \delta_1^2 \end{aligned}$$

Hence (I<sub>2</sub>) holds. Now, the proof of Theorem 1 is over.

**Proof of Theorem 2** According to theory of spectrum, we get  $H_T^1 = H^0 \oplus H^+ \oplus H^-$ , where

$$H^+ \triangleq_{j>k} \text{Ker} \left( -\frac{d^2}{dt^2} + A(t) - \lambda_j I \right)$$

$$H^- \triangleq_{j<k} \text{Ker} \left( -\frac{d^2}{dt^2} + A(t) - \lambda_j I \right)$$

$$H^0 = \text{Ker} \left( -\frac{d^2}{dt^2} + A(t) - \lambda_k I \right)$$

Let  $\varepsilon_2 = \left( \inf_{[0, T]} \liminf_{|x| \rightarrow \infty} \frac{F(t, x)}{|x|^2} - \frac{1}{2} \lambda_{k-1} \right) / 2 > 0$ . In a way similar to the proof of (8), we can prove that

$$\frac{1}{2} (\lambda_{k-1} + \varepsilon_2) |x|^2 - g'(t) \leq F(t, x) \leq \frac{1}{2} \lambda_k |x|^2 + g(t) \tag{11}$$

for all  $x \in R^N$  and a. e.  $t \in [0, T]$  by (6), where  $g'(t) \in L^1(0, T)$ . In a way similar to the proof of Lemma 1, we can prove that  $\varphi$  satisfies condition (C) by (11). As the same as in the proof of Theorem 1, we only need to prove

(I<sub>3</sub>)  $\inf_{H^+ \oplus H^0} \varphi(u) \geq d$ , where  $d$  is a constant.

(I<sub>4</sub>)  $\varphi(u) \rightarrow -\infty$ , as  $\|u\| \rightarrow \infty$  in  $H^-$ .

It follows from (11) that

$$\begin{aligned} \varphi(u) &= \frac{1}{2} \int_0^T [|\dot{u}|^2 + (A(t)u, u)] dt - \int_0^T F(t, u) dt \\ &\geq \frac{1}{2} \int_0^T [|\dot{u}|^2 + (A(t)u, u)] dt - \frac{1}{2} \lambda_k \|u\|_{L^2}^2 - \|g\|_{L^1} \geq -\|g\|_{L^1} \end{aligned}$$

for all  $u \in H^+ \oplus H^0$ , which implies (I<sub>3</sub>). It follows from (11) that

$$\begin{aligned} \varphi(u) &= \frac{1}{2} \int_0^T [|\dot{u}|^2 + (A(t)u, u)] dt - \int_0^T F(t, u) dt \\ &\leq \frac{1}{2} \lambda_{k-1} \int_0^T |u|^2 dt - \frac{1}{2} (\lambda_{k-1} + \epsilon_2) \int_0^T |u|^2 dt + \|g'\|_{L^1} \leq -\frac{\epsilon_2}{2} \int_0^T |u|^2 dt + \|g'\|_{L^1} \end{aligned}$$

for all  $u \in H^-$ . Since  $\dim(H^-) < \infty$ , there exists  $C > 0$  such that  $\|u\| \leq C \|u\|_{L^2}$  for all  $u \in H^-$ . Hence we get that  $\varphi(u) \rightarrow -\infty$  as  $\|u\| \rightarrow \infty$ . We complete the proof of Theorem 2.

Now, we give the examples to show there are functions satisfying our Theorems and not satisfying the corresponding results in [1–8].

Let  $A(t)$  be a continuous symmetric matrix of order  $N$  and

$$F(t, x) = (1 + |x|^2)^{\frac{1}{2}} \ln(1 + |x|^2) - \frac{1}{2} \lambda |x|^2 + (x, e(t))$$

for all  $x \in R^N$  and  $t \in [0, T]$ , where  $\lambda_{k-1} \leq \lambda < \lambda_k$  and  $e(t) \in L^\infty(0, T; R^N)$ . We know the functions  $A$  and  $F$  satisfy our Theorem 1 and not satisfying the corresponding results in [1–8]. Let

$$F(t, x) = \frac{1}{2} \lambda |x|^2 - (1 + |x|^2)^{\frac{1}{2}} \ln(1 + |x|^2) - (x, e(t))$$

for all  $x \in R^N$  and  $t \in [0, T]$ , where  $\lambda_{k-1} < \lambda \leq \lambda_k$  and  $e(t) \in L^\infty(0, T; R^N)$ . The functions  $F$  satisfy our Theorem 2 and not satisfy the corresponding results in [1–8].

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## 一类次二次 Hamilton 系统的周期解

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**摘要:** 运用临界点理论的极小极大方法得到一类次二次 Hamilton 系统的周期解的可解性条件.

**关键词:** 次二次哈密顿系统; 可解性条件; 周期解

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